

Stefanos Pertigkiozoglou

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Education

Ph.D. in Computer Science, University of Pennsylvania (GRASP Lab) (2019-Present)

Advisor: Kostas Daniilidis

Research Interests: Geometric Deep Learning, 3D Vision

MSc in Robotics, University of Pennsylvania (2019-2024)

GRASP Lab, GPA: 4.0/4.0

Integrated Bachelor's and Master's in Electrical and Computer Engineering (2012-2018)

National Technical University of Athens

GPA: 9.42/10, summa cum laude, Class rank: Top 2%

Undergrad Advisor: Petros Maragos

Thesis: Detecting Adversarial Examples in Convolutional Neural Networks

Research Interests

Computer Vision, Geometric Deep Learning, Equivariant representations, Point Cloud Processing, 3D Vision, Neural Rendering and Reconstruction

Publications

SE(3)-Equivariant Attention Networks for Shape Reconstruction in Function Space

E. Chatzipantazis*, S. Pertigkiozoglou*, E. Dobriban, K. Daniilidis, ICLR 2023

Proposed an SE(3)-Equivariant Transformer network for shape reconstruction given input point cloud scans. Showed how the equivariant constraint along with the use of local shape modeling enables the model, trained on single objects, to generalize to scene reconstruction.

Learning Augmentation distributions using transform risk minimization

E. Chatzipantazis*, S. Pertigkiozoglou*, K. Daniilidis, E. Dobriban, Transactions of Machine Learning Research 2023

Proposed Transformed Risk Minimization (TRM) as an extension of the standard risk minimization. TRM allows for simultaneously learning a model and a distribution of useful training and testing augmentations that improve the overall task performance.

Detecting Adversarial examples in convolutional neural networks

S. Pertigkiozoglou, P. Maragos, arXiv 2018.

Investigated the adversarial robustness of Convolutional Neural Networks and proposed different techniques for detecting inputs that are perturbed by a set of adversarial attacks.

Manuscripts under review

Diffusion models for Open Vocabulary Object Navigation

A. P. Singh, S. Pertigkiozoglou, B. Wu, G. Georgakis, K. Daniilidis

Proposed a diffusion model that can generate paths allowing an agent to navigate an unknown environment and find a specified object. The diffusion model is conditioned with a predicted feature map that encodes the environment using CLIP embeddings. This conditioning allows the method to take as input an arbitrary description of the query object, without the limitation of a predefined set of object categories

Robust Point Cloud Registration via Equivariant Representations

S. Pertigkiozoglou*, E. Chatzipantazis*, K. Daniilidis

Proposed a novel point cloud registration method that uses equivariant representations to achieve robust point cloud alignment. The use of equivariant representations allows for a consistent registration that is independent of the initial poses of the input point clouds.

* Denotes equal contribution

Technical Reports and Projects

Shape Space and the Geodesics between Shapes (2023) [pdf]

A presentation of fundamental concepts of the Shape Space theory and the computation of geodesic in shape space that allows for interpolation between shapes.

Adversarial Robustness in Model Ensembles (2021) [pdf]/[code]

In this work we investigated the adversarial robustness of ensembles of models. Then we proposed a generalization of the classical boosting methods as a way of reducing the adversarial error of such ensembles.

Designing a Distributed Website Crawler (2020) [code]

Implementation of a distributed website crawler. The distributed crawler heads are designed so that they can be individually deployed in EC2/AWS instances.

Experience

Graduate Research Assistant

(Sep. 2019-Present)

GRASP Lab, University of Pennsylvania

My research interests lie in the intersection of Computer Vision and Geometric Deep Learning.

- Designed equivariant methods that enable models to learn representations of geometric objects and perform tasks such as shape reconstruction or point cloud registration consistently, independent of the arbitrary choice of reference frame.
- As part of the multidisciplinary ARO-MURI project for robust concept learning, we proposed the Transformed Risk Minimization (TRM) that can discover symmetries existing in the data and augmentation distributions that are useful during both training and testing.

Research Assistant

(Sep. 2018- Aug. 2019)

CVSP Lab, National Technical University of Athens

As a part of my thesis, I designed methods for detecting adversarially perturbed inputs to neural networks, and I investigated how properties such as the Lipschitz constant of a model correlate to its adversarial robustness.

Teaching Experience

- Teaching Assistant, CIS 580: Machine Perception (Head TA), Spring 2021
- Teaching Assistant, CIS 680: Advance Topics in Machine Perception, Fall 2020

Academic Reviewer: ICCV, CVPR, ICLR, Neurips

Technical Skills

Proficient Use: Python, PyTorch, \LaTeX , Git, Linux

Basic Use: C++, TensorFlow, Blender, Java

Honors and Awards

- **Gerondelis Foundation, Graduate School Grant**, 2023
- **Thomaideion Award** for the highest grades among all students in Electrical and Computer Engineering during the academic year 2012-2013
- **Chris Papakiriakopoulos Award** for academic excellence in Mathematics during the academic year 2012-2013